



Lightweight, Low-Power IP

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The Message

- IP is lightweight
 - ... but weight has performance implications
- IP is small
 - ... but means API changes
- IP is power-efficient
 - ... but low power subtly affect the system

id -G -n

IWIP

uIP

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IWIP

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TCP/IP Enabled Lego Brick

Posted by [timothy](#) on Tue Jan 29, 2002 05:12 PM
from the [snap-snap-ping](#) dept.

An anonymous reader submits:

"Yesterday, Olaf Christ announced that he has [the world's first](#) brick that can be used as a web server. Imagine the poss

[InfoSatellite.com](#) / News

Lego hackers bring TCP/IP to Mindstorms

By [Oystein W. Hoie](#)
[InfoSatellite.com](#)
January 30, 2002

Reprogramming and modifying Lego's Mindstorms set to create robotics has become the latest craze in the community. A while ago, a universal RCX language was translated to C++, and today, the first offering full TCP/IP support was announced. Being able to connect the Internet, the possibilities are endless.

Toys have been part of the technological revolution society has seen in the last couple of months, and so has the classic company Lego. Robot sets such as Mindstorms come with a programmable computer that is able to function as the brain of a robot, interfacing with the outside world through a range of sensors.

Considering that a majority of buyers



advertisement

Where am I? > Home > News > Hacking

Latest hacker toy? Web-enabled Lego

'Christ' creates world's first TCP/IP-enabled RCX

Written by [James Middleton](#)
[vnunet.com](#), 30 Jan 2002

We've seen web servers that fit into matchboxes, but now a protocol hacker has created the first web-enabled Lego brick.

By porting the extremely small uIP TCP/IP (transmission control protocol/inter) to the Lego Mindstorms platform, Olaf Christ has set the foundations for a Lego k

uIP

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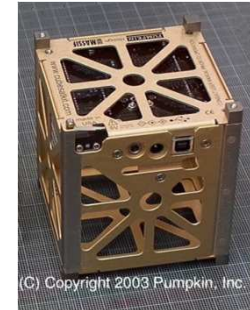
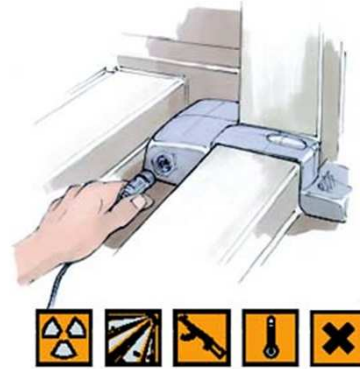
SICS



(and many more)

Contiki uIPv6

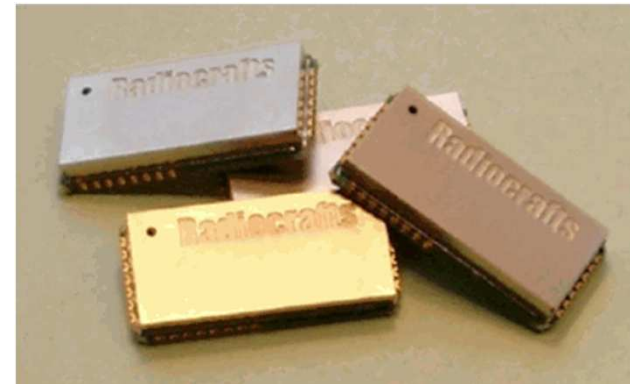




Fundamental Challenges

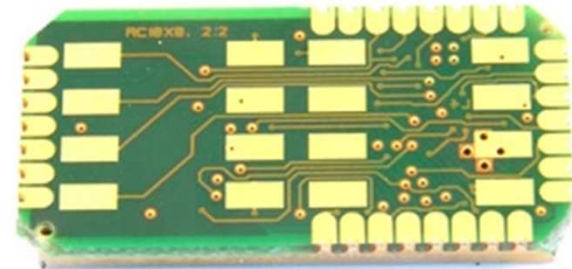
Fundamental Challenges

- Cost
- Physical size
- Energy
 - Batteries
- Power
 - Energy scavenging
- Wireless/lossy communication
 - Bandwidth
 - Lossy links
- Lack of visibility



Device-level Implications

- Small memory size
 - Kilobytes of RAM
- Simple processor
 - Megahertz
 - No MMU
- Example: MSP430f1449
 - 8 kb RAM, 40 kb ROM



Memory

The size of TCP/IP

- "IP is heavyweight"
 - Linux, BSD stacks 200+ kb code, 300+ kb RAM
- lwIP: TCP/UDP/ICMP/IPv4 in 30 kb ROM
- uIP: TCP/UDP/ICMP/IPv4 in 5 kb ROM
- uIPv6: TCP/UDP/ICMPv6/IPv6 in 13 kb ROM

uIP: Making IP Small

- Shared packet buffer
- Event-driven API

Shared packet buffer

- **All** packets – both outbound and inbound – use the same buffer
- Size of buffer determines throughput



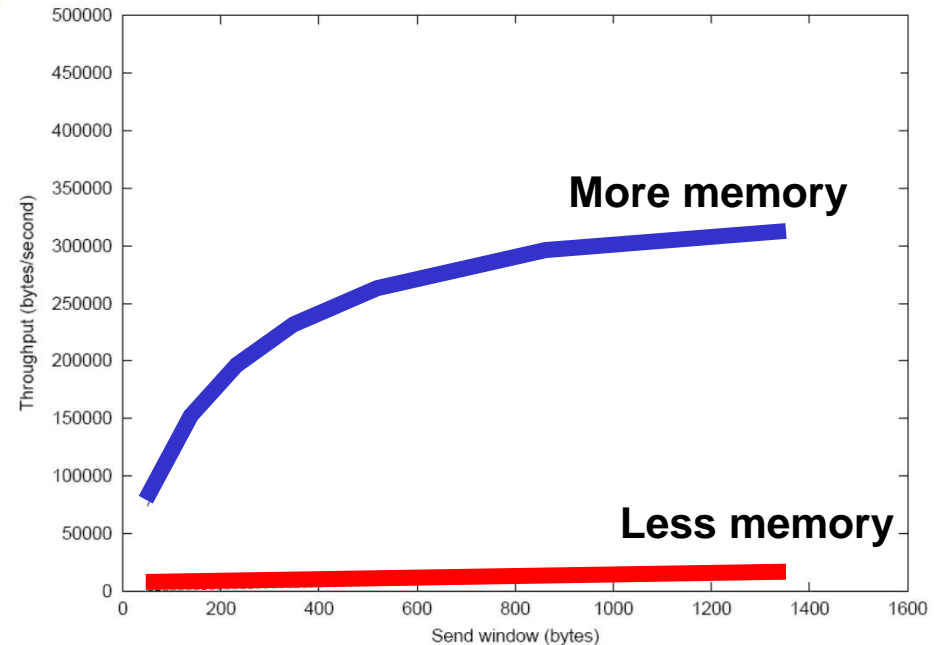
Shared packet buffer II

- Implicit locking: single-threaded access
 - 1) Grab packet from network – put into buffer
 - 2) Process packet
 - Put reply packet in the same buffer
 - 3) Send reply packet into network



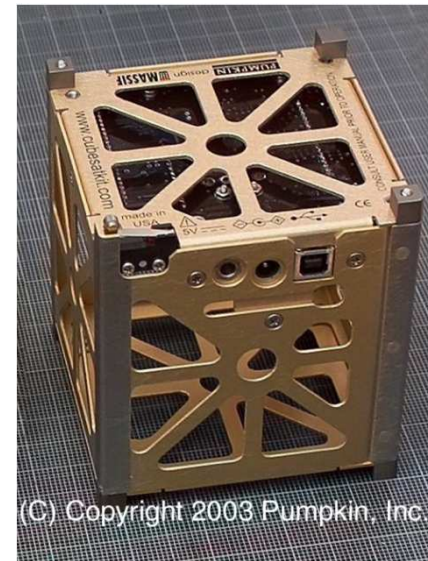
Throughput

- ulP trades throughp
- Low RAM usage = lo
- Small systems = no
- Current work:
 - Improve TCP throughput by low-power pipelined forwarding



Example: uLP-based Pico Satellite

- CubeSat pico satellite
 - MSP430-based
 - 128 bytes of RAM for uLP



Application Programming Interface I

- uIP does not have BSD sockets
 - BSD sockets are built on threads
 - Threads induce overhead (RAM)
- Instead – event-driven API
- Execution is always initiated by uIP
 - Applications are called by uIP, call must return
- Protosockets – BSD socket-like API based on protothreads

Application Programming Interface II

```
void example2_app(void) {  
    struct example2_state *s =  
        (struct example2_state *)uip_conn->appstate;
```

```
    if(uip_connected()) {  
        s->state = WELCOME_SENT;  
        uip_send("Welcome!\n", 9);  
        return;  
    }
```

```
    if(uip_acked() &&  
        s->state == WELCOME_SENT) {  
        s->state = WELCOME_ACKED;  
    }
```

```
    if(uip_newdata()) {  
        uip_send("ok\n", 3);  
    }
```

```
    if(uip_rexmit()) {  
        switch(s->state) {  
            case WELCOME_SENT:  
                uip_send("Welcome!\n", 9);  
                break;  
            case WELCOME_ACKED:  
                uip_send("ok\n", 3);  
                break;  
        }  
    }
```

Application Programming Interface III

- Event-driven API sometimes is problematic
 - Not all programs are well-suited to it
 - Programs are explicit state machines
- Protosockets: sockets-like API using protothreads
 - Extremely lightweight stackless threads
 - 2 bytes per-thread state, no stack
- Protothreads allow “blocking” functions, even when called from uIP

Application Programming Interface IV

```
PT_THREAD(smtp_protothread(void))
{
    PSOCK_BEGIN(s);

    PSOCK_READTO(s, '\n');

    if(strncmp(inputbuffer, "220", 3) != 0) {
        PSOCK_CLOSE(s);
        PSOCK_EXIT(s);
    }

    PSOCK_SEND(s, "HELO ", 5);
    PSOCK_SEND(s, hostname, strlen(hostname));
    PSOCK_SEND(s, "\r\n", 2);

    PSOCK_READTO(s, '\n');

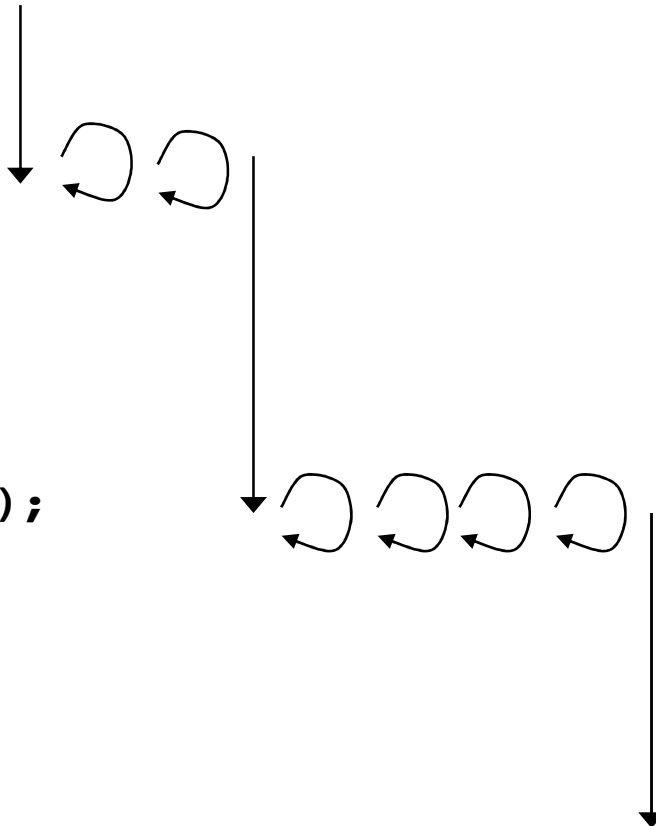
    if(inputbuffer[0] != '2') {
        PSOCK_CLOSE(s);
        PSOCK_EXIT(s);
    }
}
```

Protothreads: Lightweight, thread-like programming

- A design point between events and threads
- Programming primitive: conditional blocking wait
 - `PT_WAIT_UNTIL(condition)`
- Single stack
 - Low memory usage, just like events
- Sequential flow of control
 - No explicit state machine, just like threads
 - Programming language helps us: **if** and **while**

An example protothread

```
int a_protothread(struct pt *pt) {  
    PT_BEGIN(pt);  
    /* ... */  
    PT_WAIT_UNTIL(pt, condition1);  
    /* ... */  
    if(something) {  
        /* ... */  
        PT_WAIT_UNTIL(pt, condition2);  
        /* ... */  
    }  
    PT_END(pt);  
}
```



Six-line implementation

Protothreads implemented using the C switch statement

```
struct pt { unsigned short lc; };

#define PT_INIT(pt)          pt->lc = 0
#define PT_BEGIN(pt)        switch(pt->lc) { case 0:
#define PT_EXIT(pt)         pt->lc = 0; return 2
#define PT_WAIT_UNTIL(pt, c) pt->lc = __LINE__; case __LINE__: \
                            if(!(c)) return 0
#define PT_END(pt)          } pt->lc = 0; return 1
```

C-switch expansion

```
int a_protothread(struct pt *pt) {
    PT_BEGIN(pt);

    PT_WAIT_UNTIL(pt, condition1);

    if(something) {

        PT_WAIT_UNTIL(pt, condition2);

    }

    PT_END(pt);
}
```

```
int a_protothread(struct pt *pt) {
    switch(pt->lc) { case 0:

        pt->lc = 5; case 5:
        if(!condition1) return 0;

        if(something) {

            pt->lc = 10; case 10:
            if(condition2) return 0;

        }

    } return 1;
}
```

Line numbers

Memory

- Yes, IP can be done in small amounts of memory
 - But may affect performance
- Event-driven interfaces, bottom-up design, static memory allocations reduce memory
 - But changes the API

Power and Energy

Power and Energy are Crucial

- Unattended operation, long lifetime
- Battery-powered nodes
 - Replacement, recharging not feasible/possible
- Energy generation
 - Low power

Radio Power Consumption

- Radio dominates power consumption
- Listening as expensive as transmitting

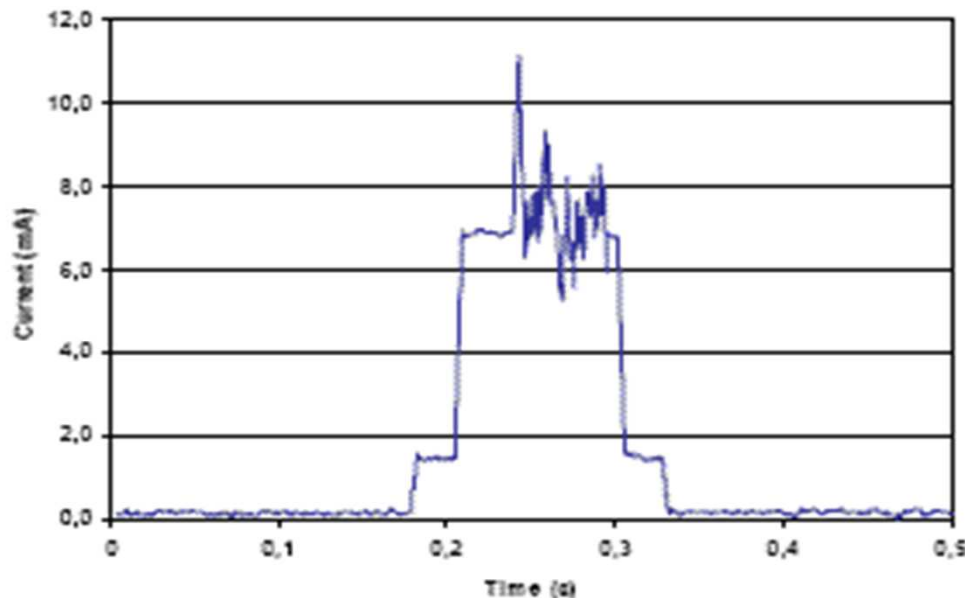


Figure 6. Power consumption: sending

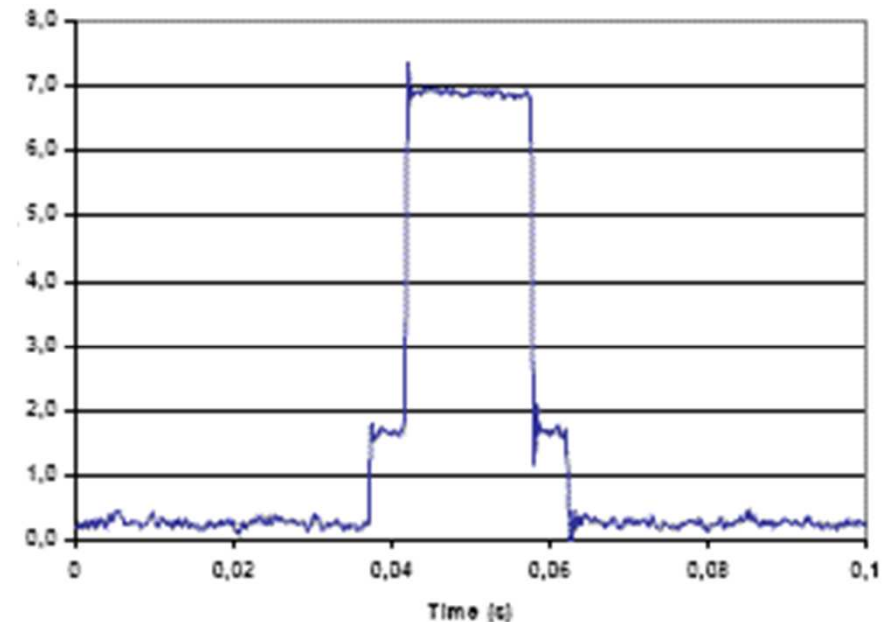
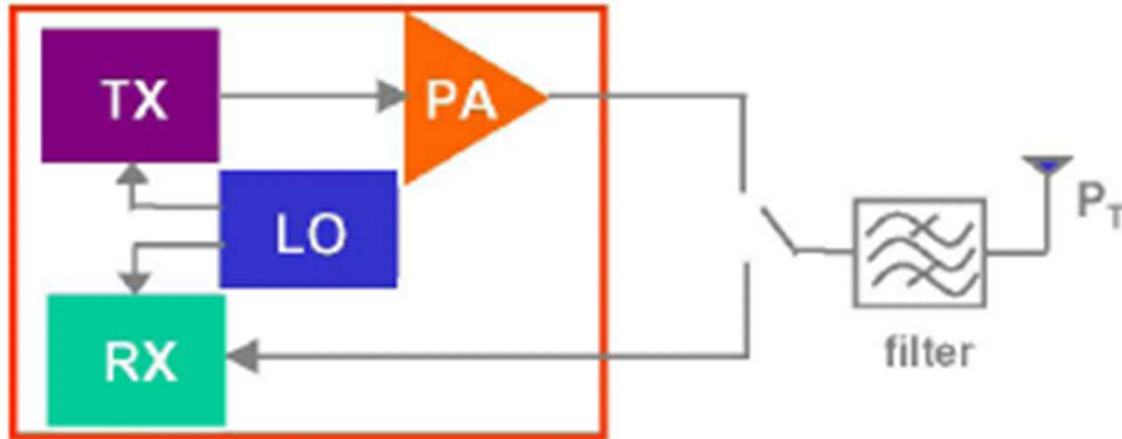


Figure 7. Power consumption: receiving

Why is Listening More Expensive than Transmitting?



RF transceiver

	GSM	802.11b	Bluetooth
$P_{RX} + P_{LO}$ (mW)	240	60	30
$P_{TX} + P_{LO}$ (mW)	360	100	12
P_T (mW)	1000	100	1
P_{PA} (mW)	2500	250	2.5
η_P	32%	24%	2%

Source: Wang & Sodini, ICC 2006

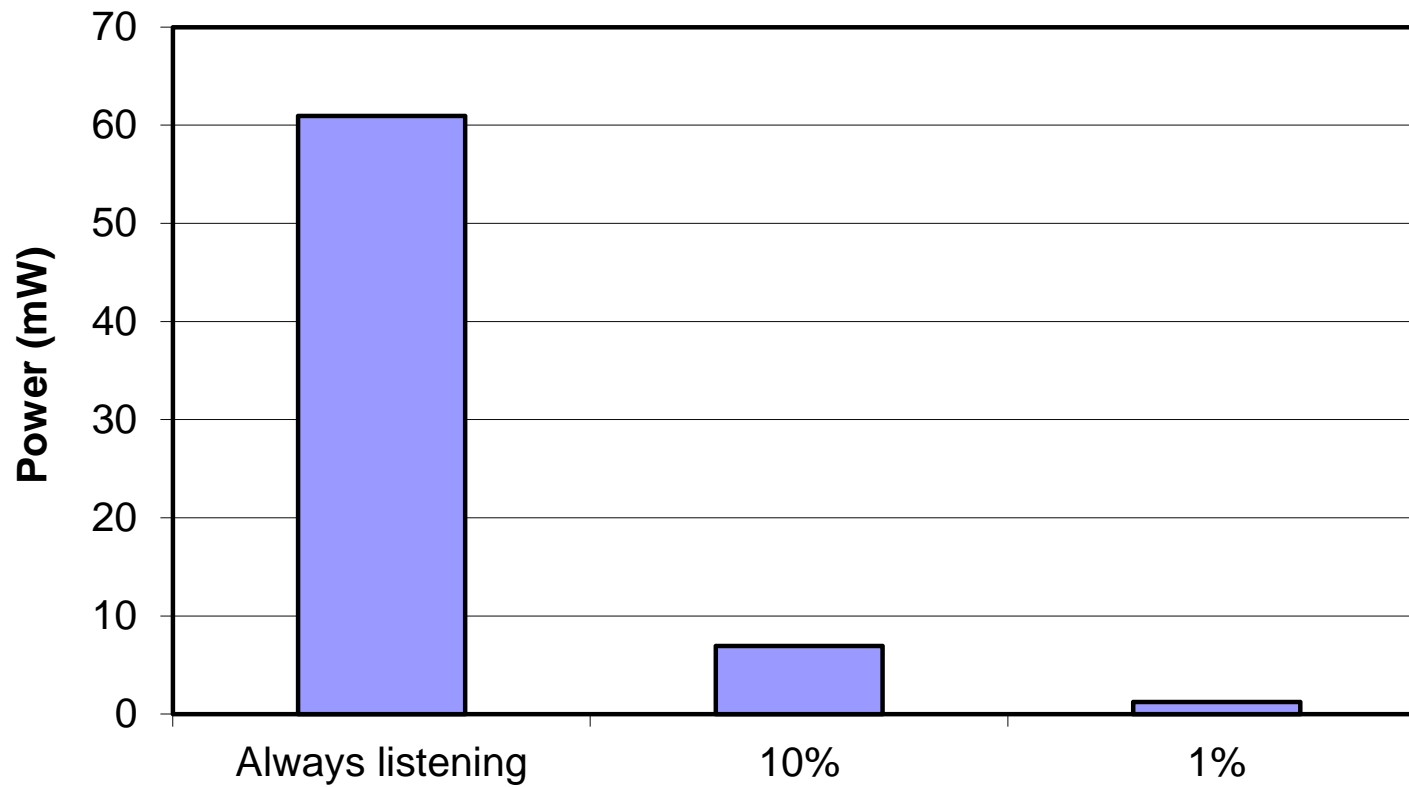
Low-power radio hardware

- IEEE 802.15.4 (250 kilobits/second)
 - Power ~60 mW
 - Sleep ~0.01 mW
 - Range 40 m
- Low-power WiFi (2-50 megabits/second)
 - Power ~300 mW
 - Sleep ~0.02 mW
 - Range 400 m

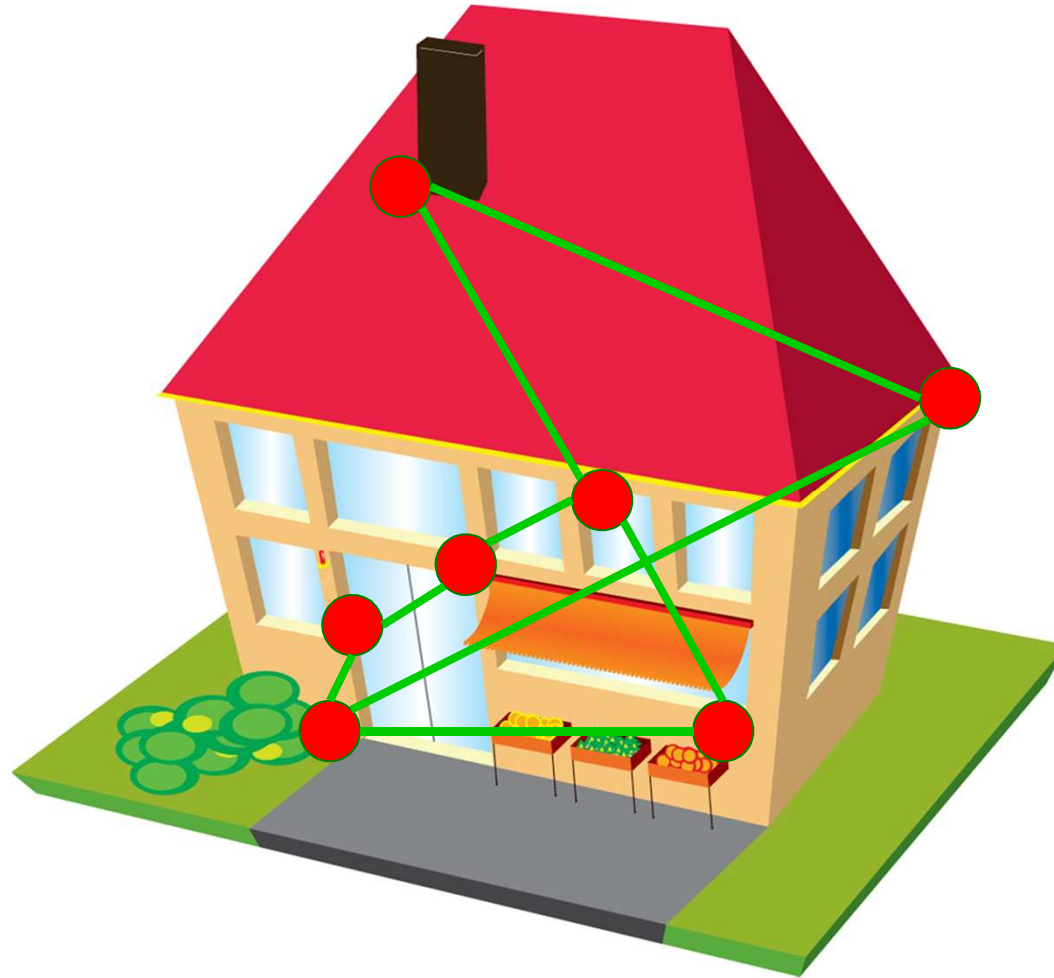
Listening is Expensive

- Being always on kills you quickly
 - Days of lifetime on batteries
- What about always sleeping?
 - Waking up only to send
 - Wake up on the hour, every hour
 - Introduces strange semantics
 - What about multi-hop?

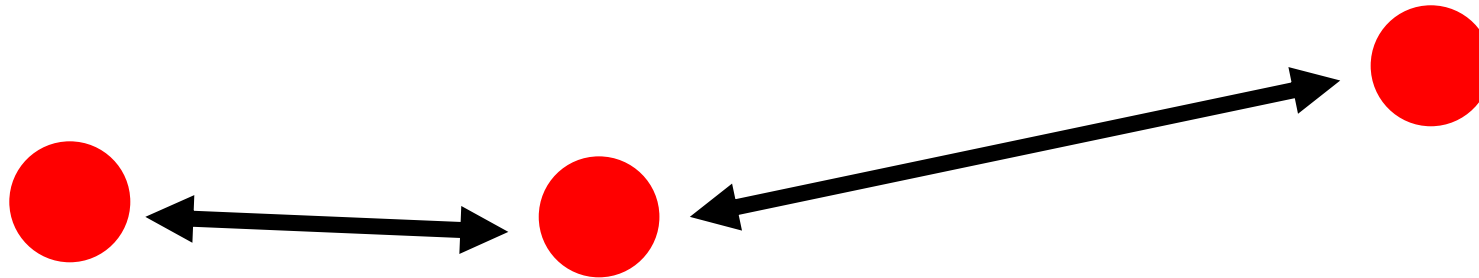
Listening is expensive



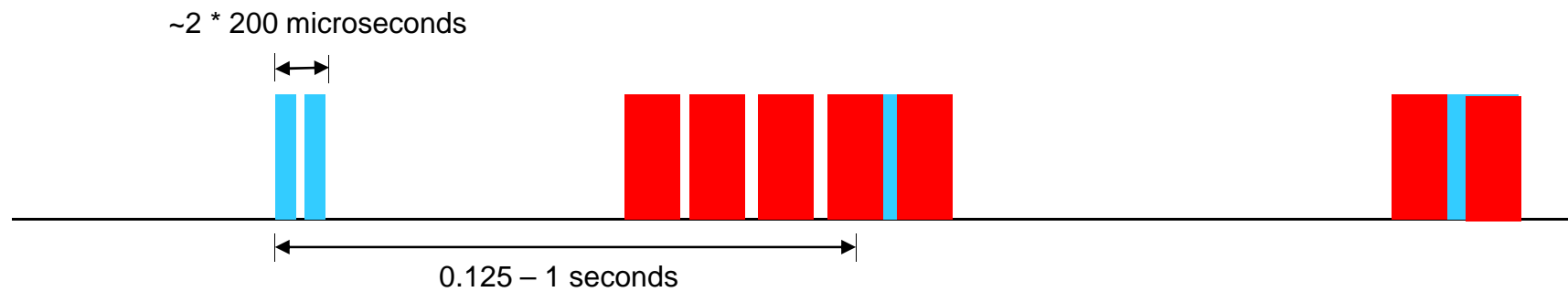
Multi-hop communication



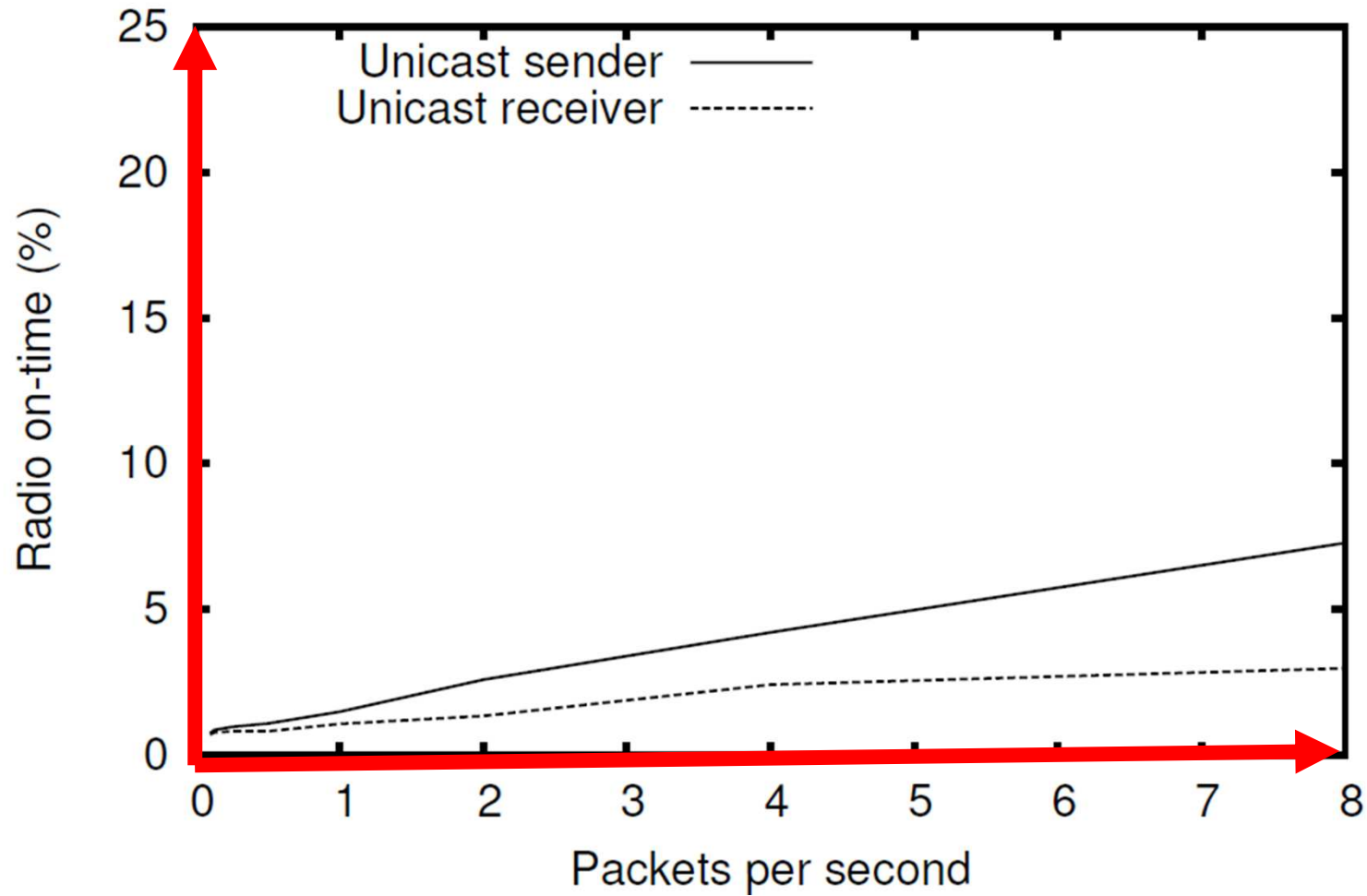
Multi-hop communication



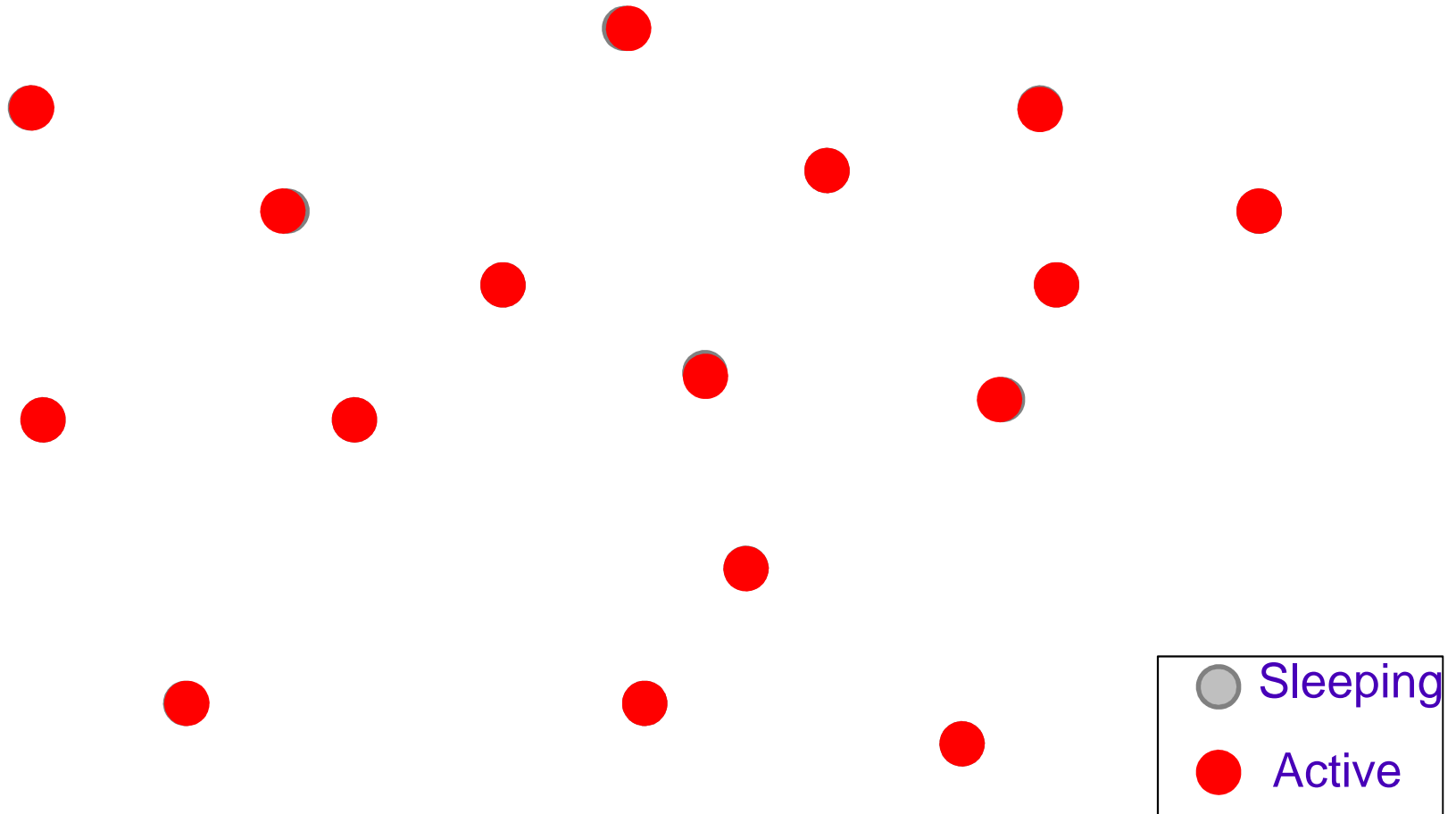
Duty Cycling (ContikiMAC)



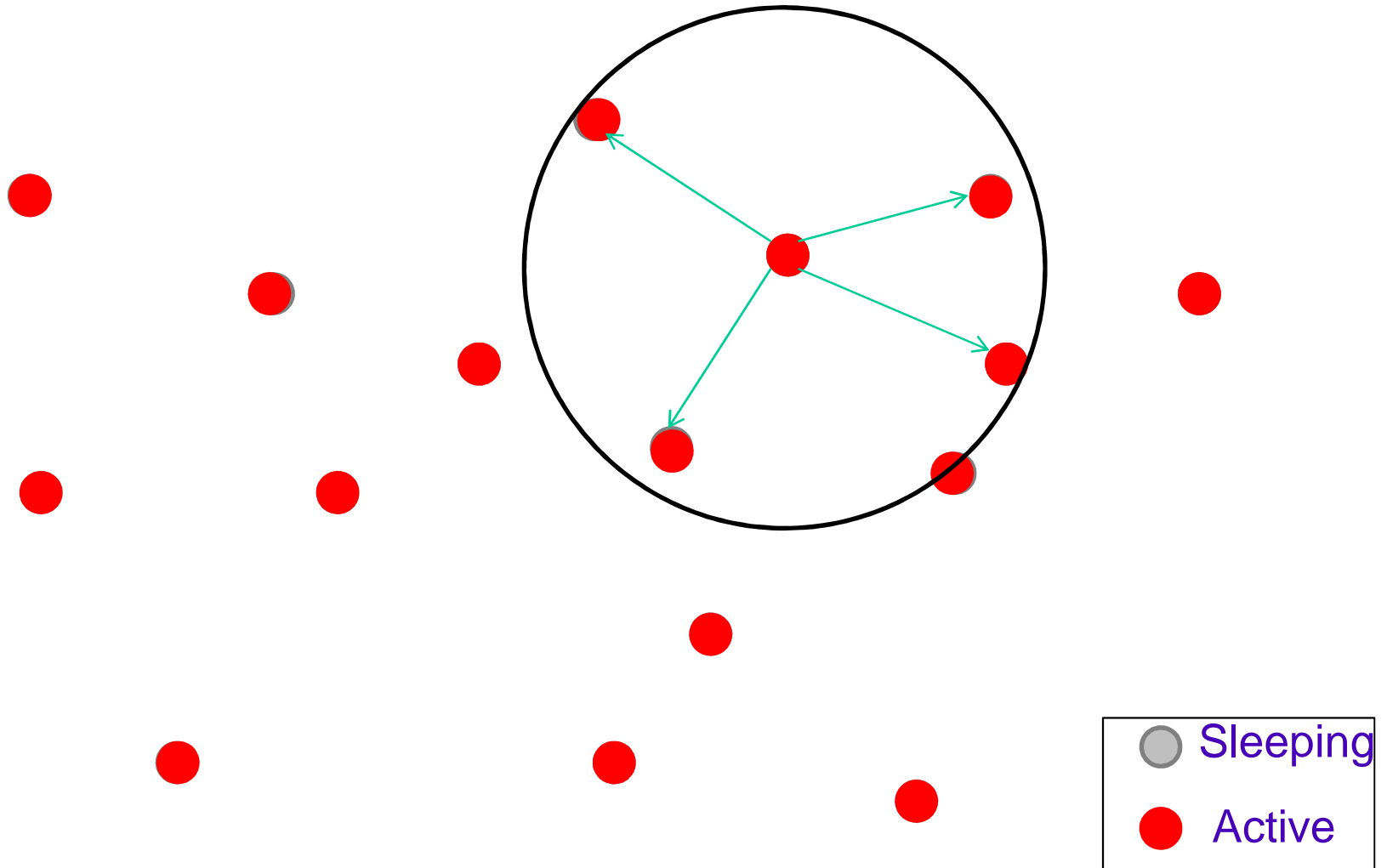
Efficiency



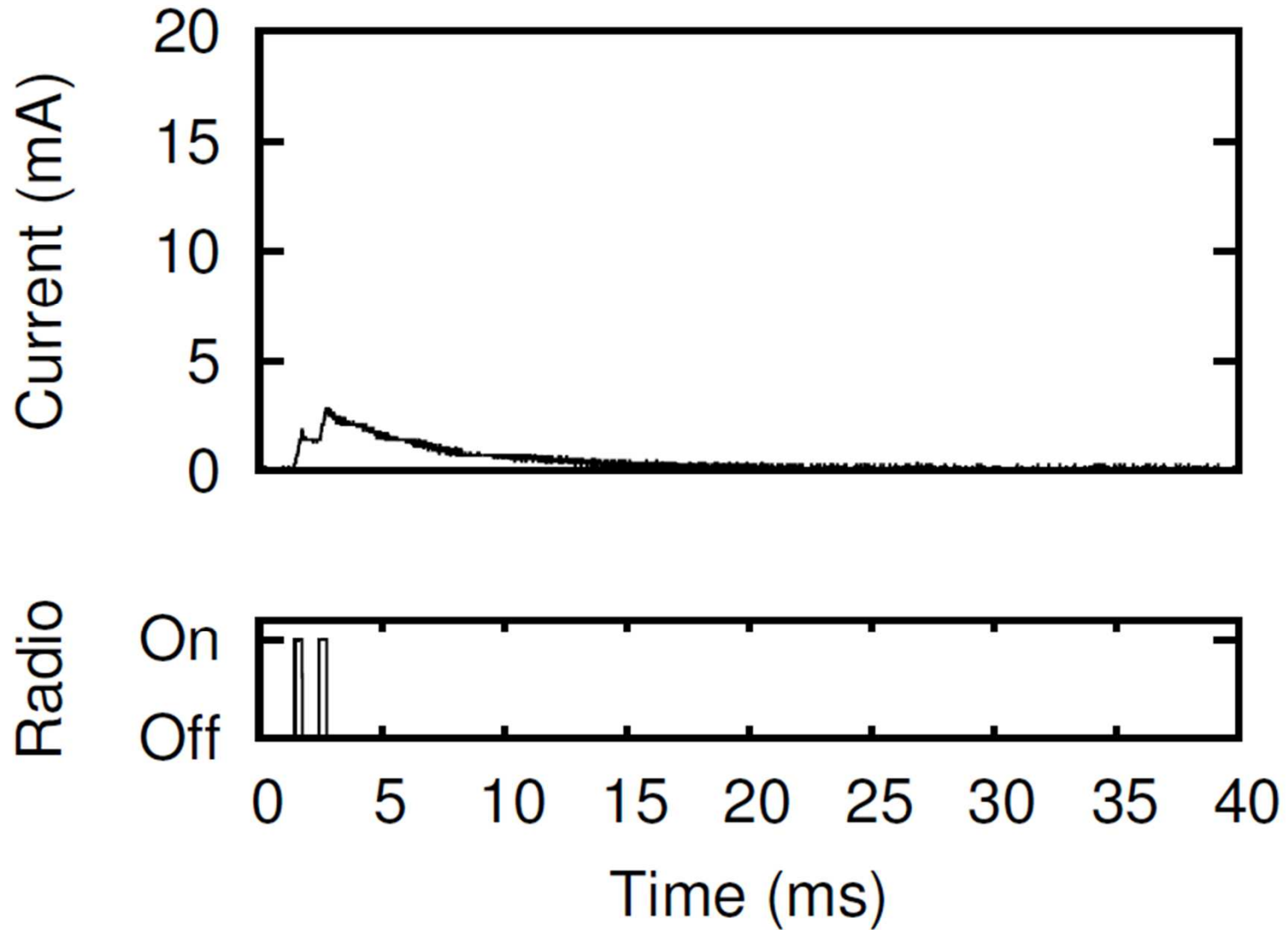
Duty Cycling



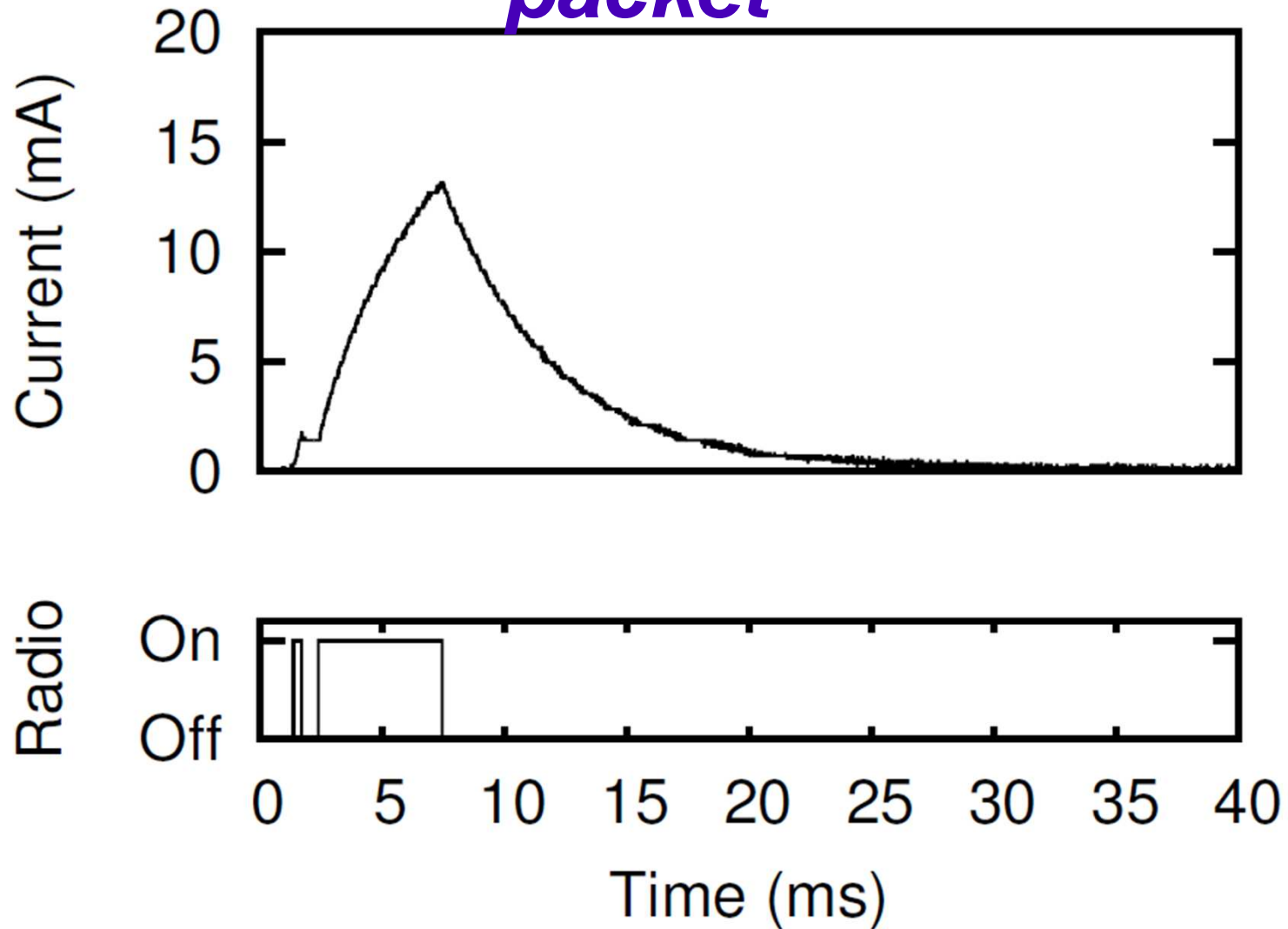
Broadcast with Duty Cycling



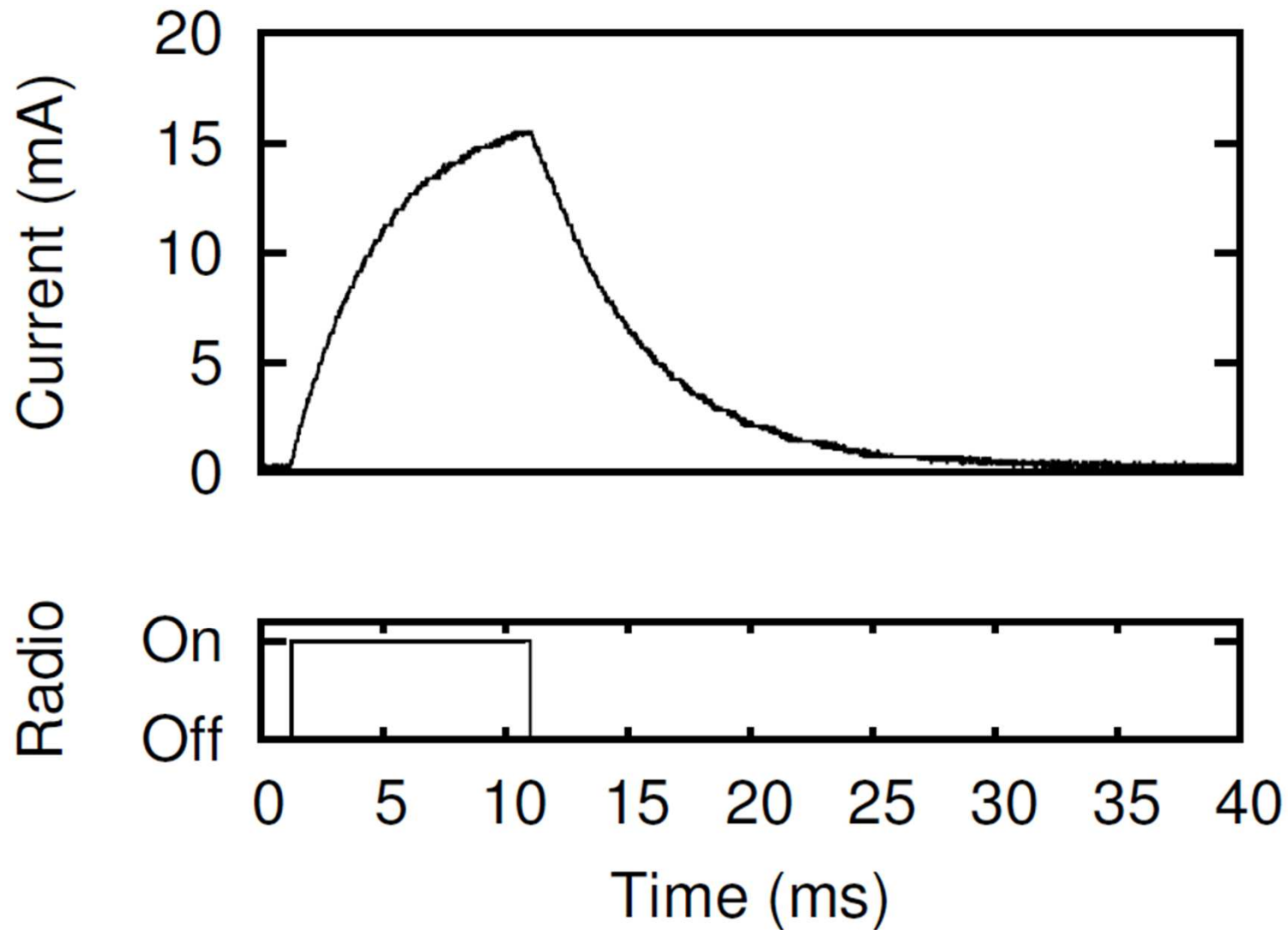
Wake-up



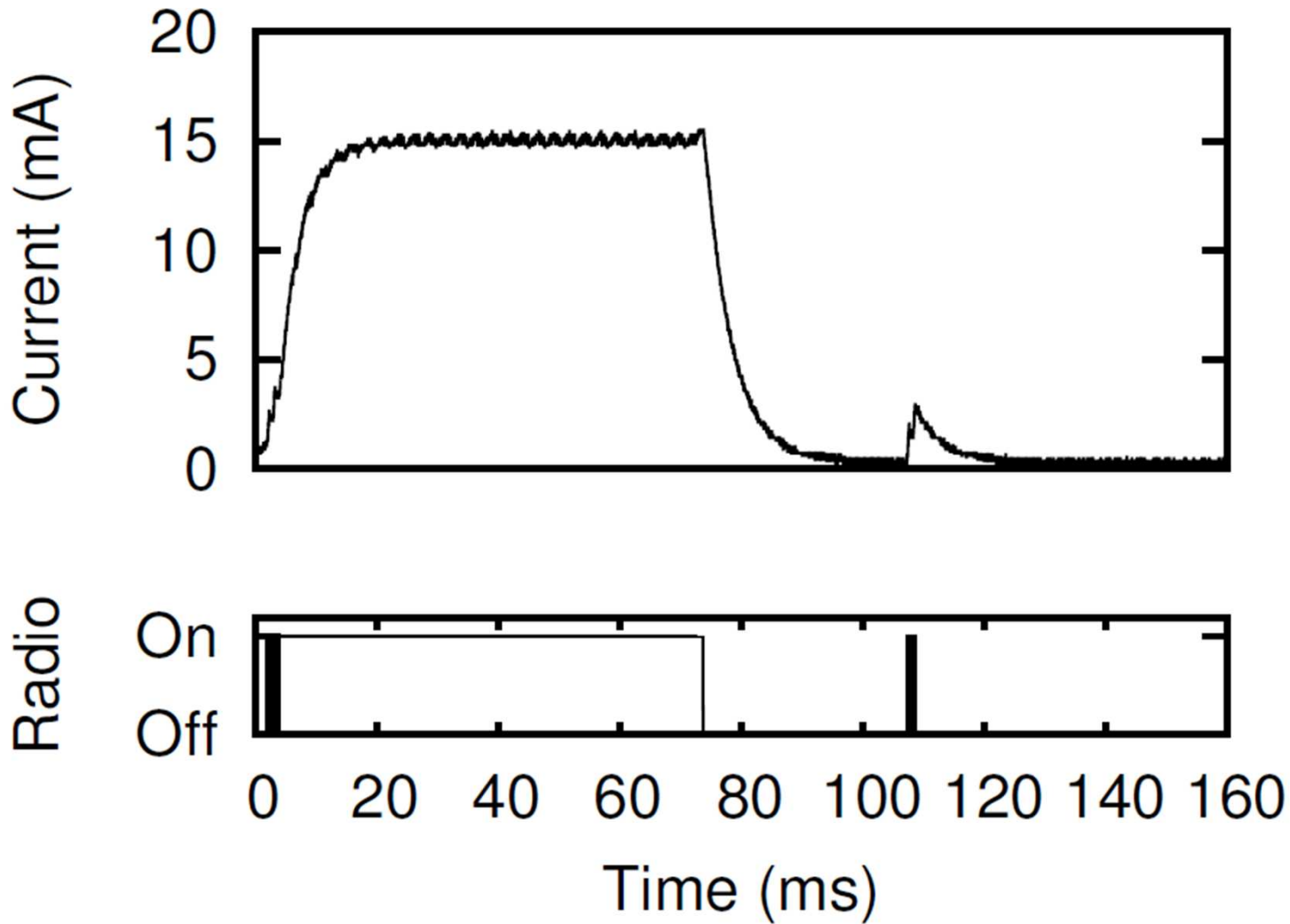
Wake-up, signal detected but no packet



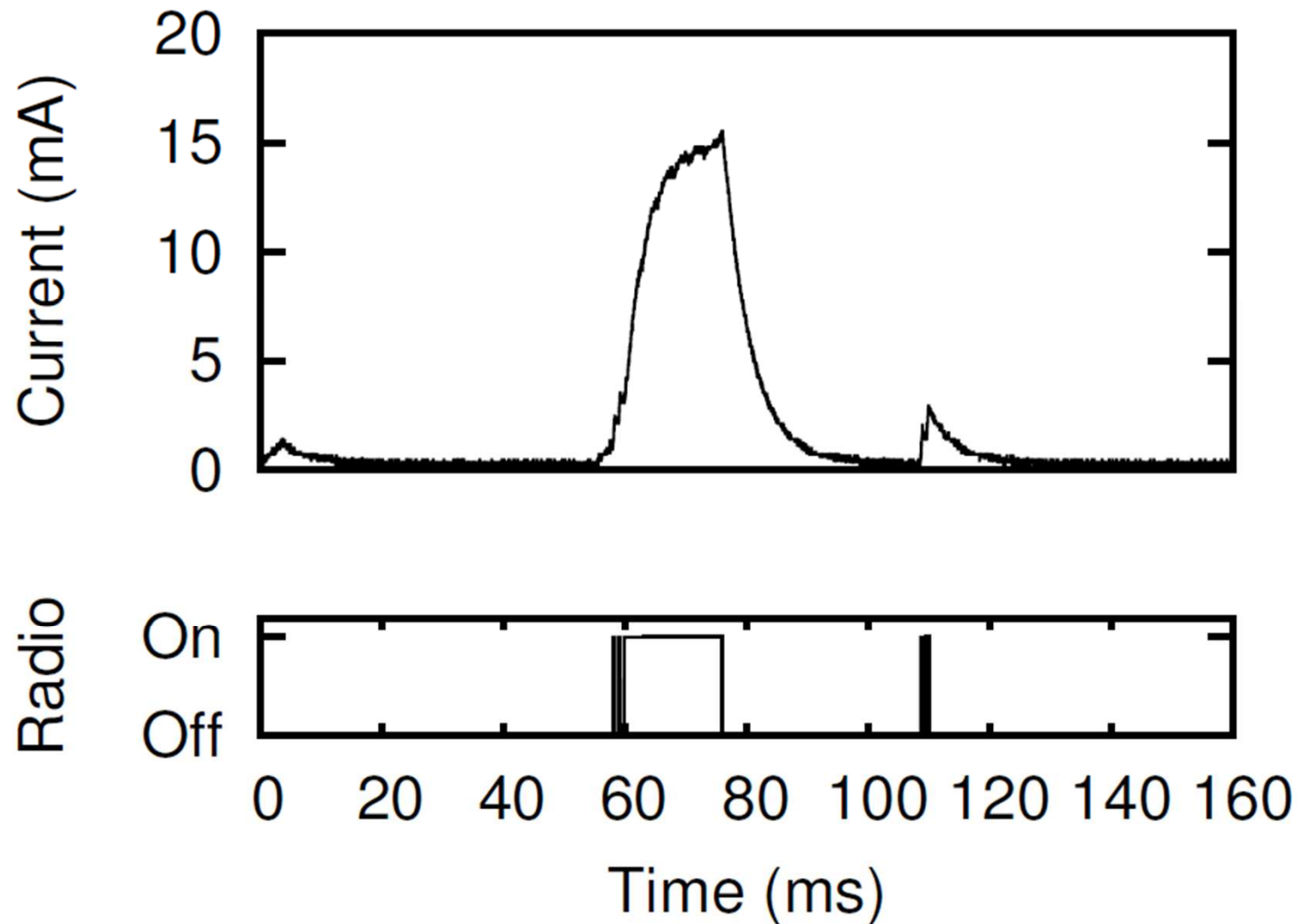
Reception



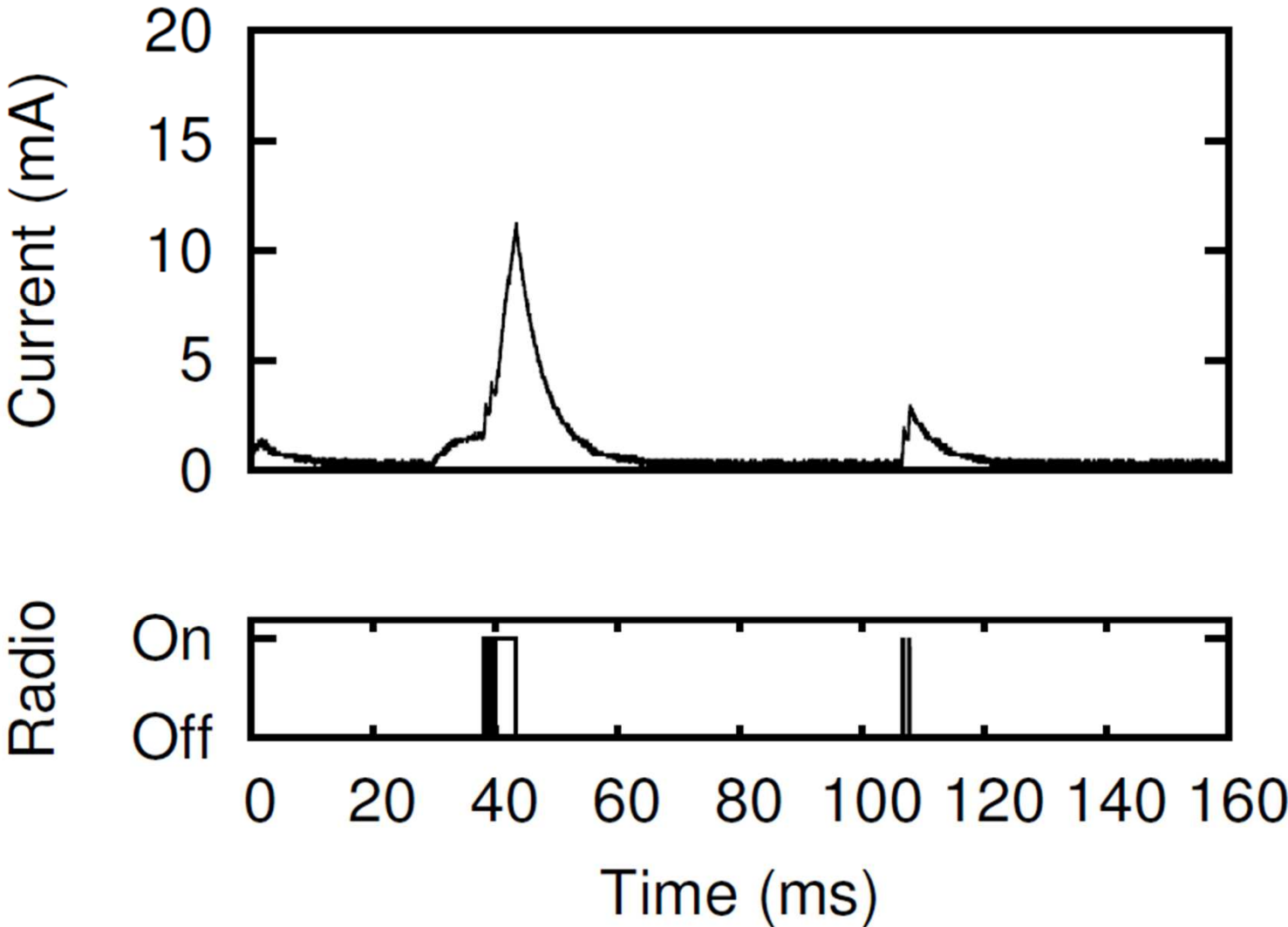
Unicast transmission, first time



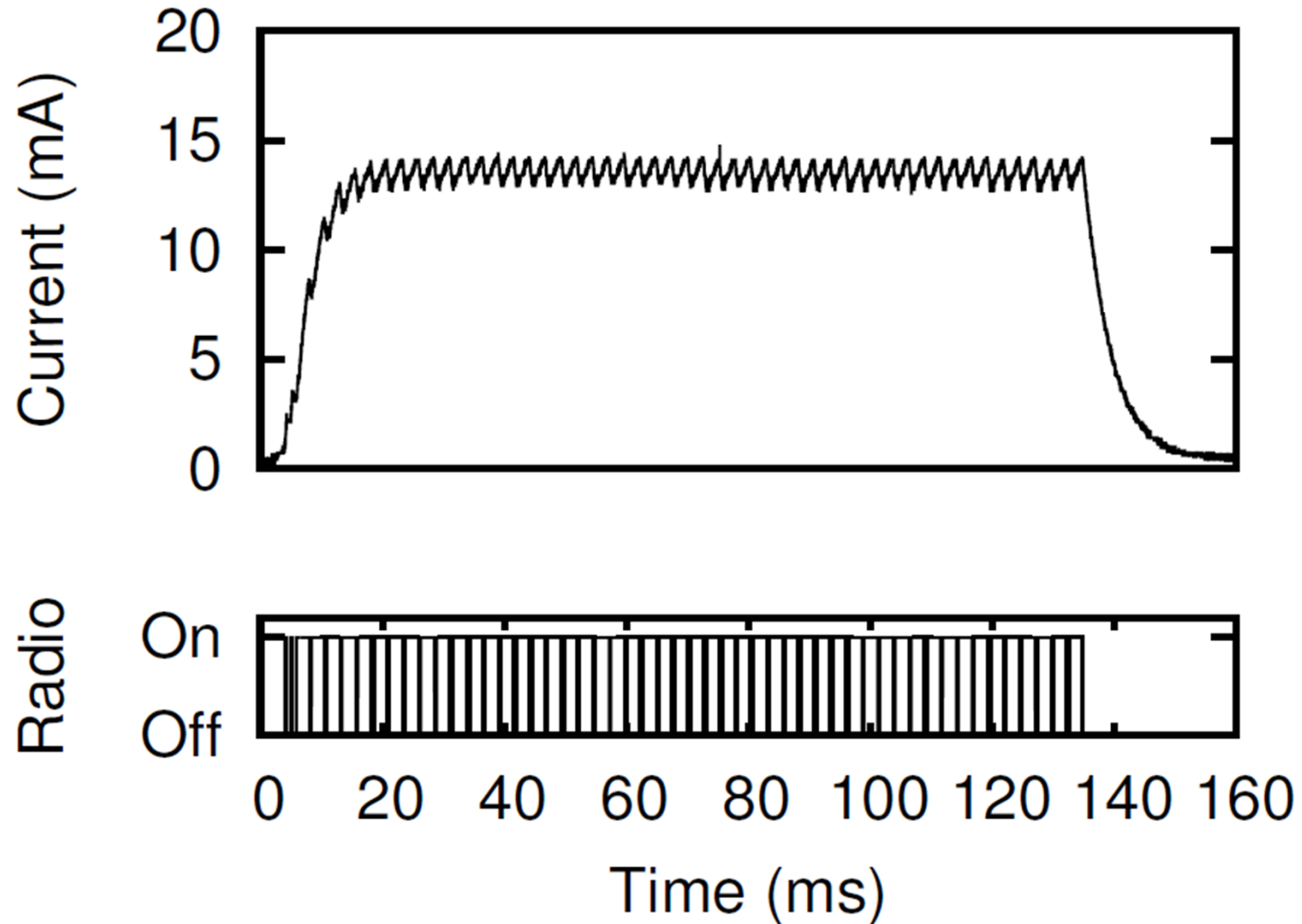
Unicast transmission, second time



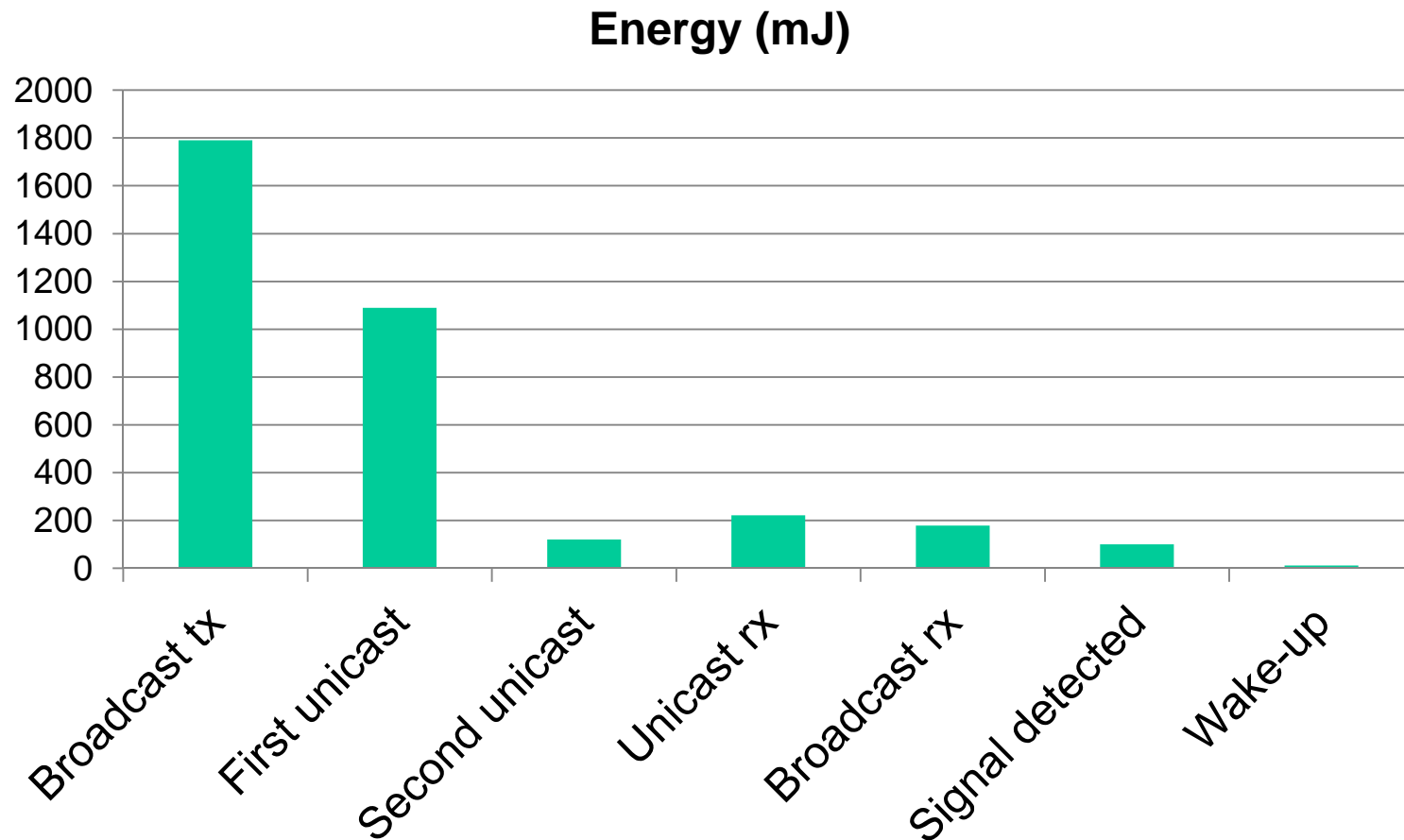
Unicast Tx to Awake Neighbor



Broadcast transmission



Energy

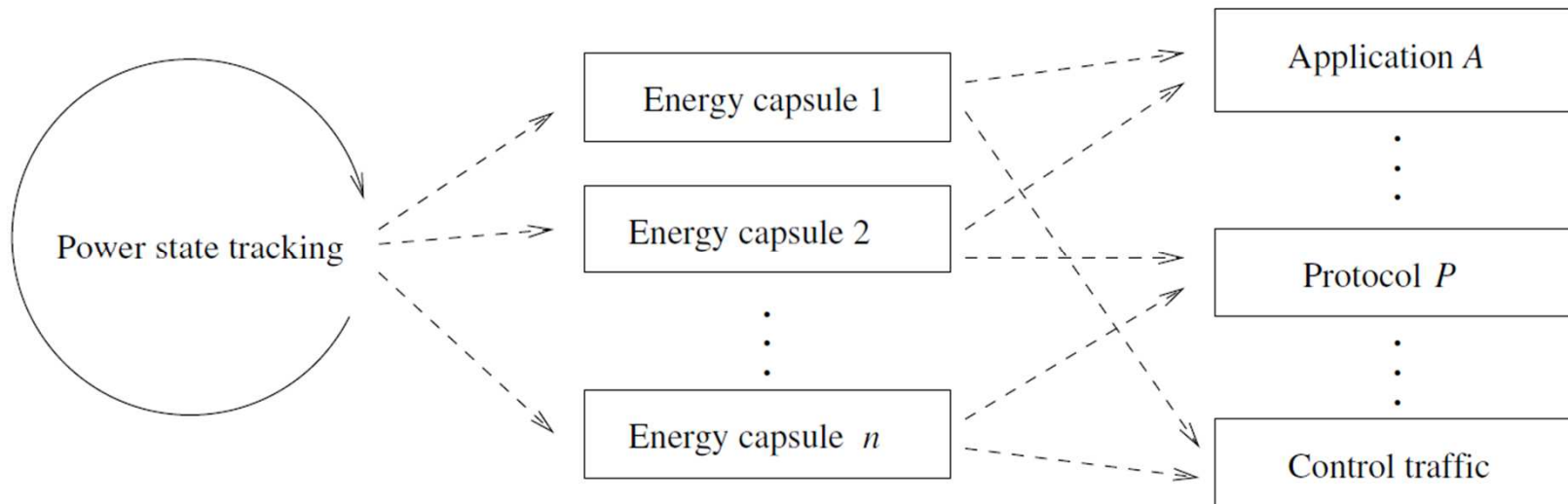


Broadcast in Low-power Wireless

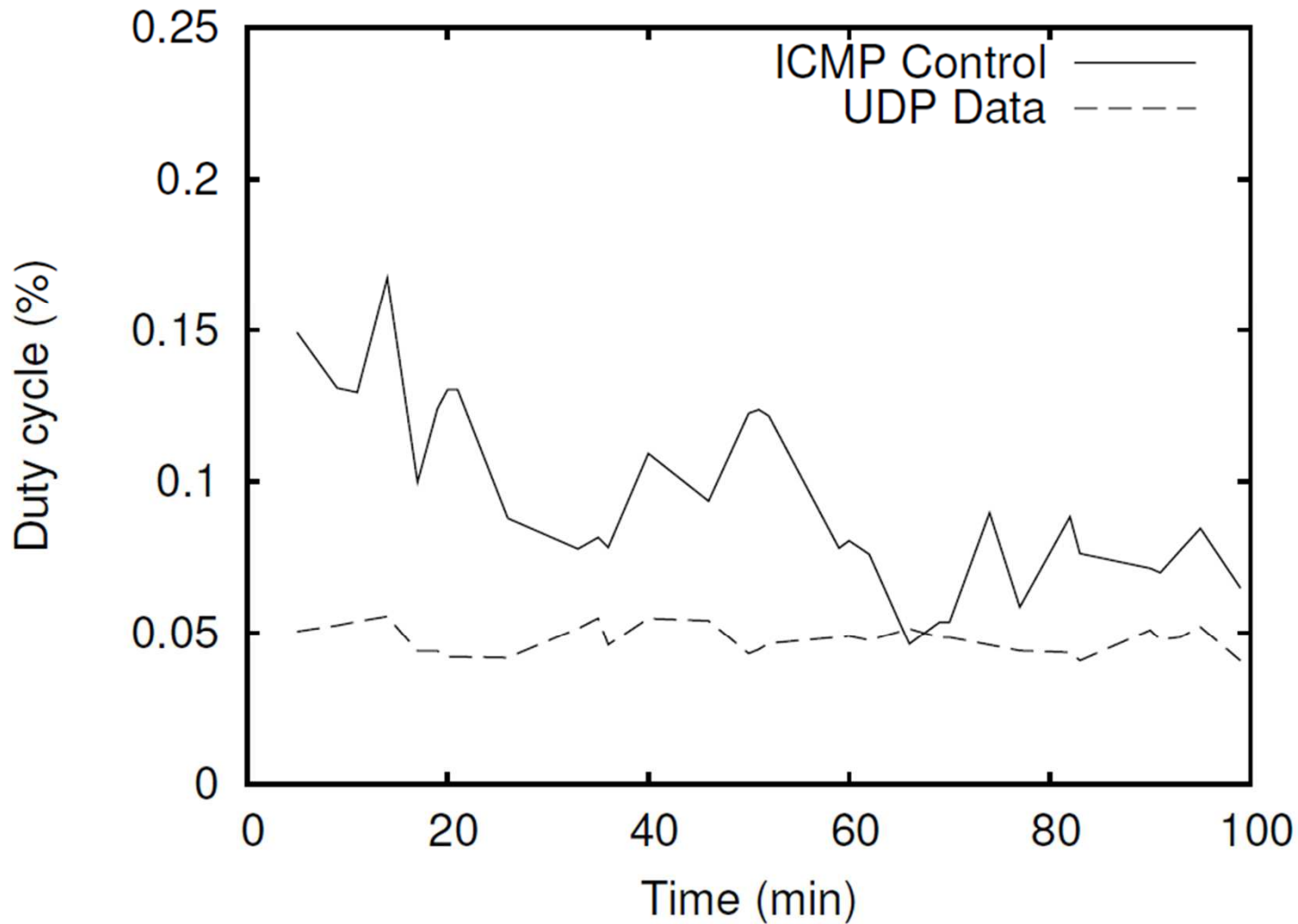
- Semantics slightly changed
 - Not necessarily atomic
 - Not necessarily synchronous
- Quantitative changes
 - Broadcast more expensive than unicast

Contiki Powertrace

- Network-level energy estimation
- Power state tracking, energy capsules
- Energy attribution to network-level activities



Power Consumption in RPL



What to do about Broadcast?

- Still an open question
 - Adaptive beaconing (CTP)
 - Beacon suppression (Trickle, RPL)
 - Beacon coordination (Dunkels et al, EWSN 2011)
 - Politecast (Lunden and Dunkels, ACM CCR April 2011)

Alternatives to Asynchronous Duty Cycling

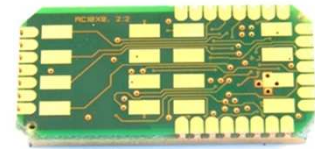
- Sleepy nodes
 - Never wake up to receive
 - But fundamentally changes semantics of IP
- Time-synchronized wake-ups
 - Schedule wake-ups at known times, schedule broadcast slot
 - Makes broadcast and unicast equivalent, but spends idle energy on broadcast anyway

Power and Energy

- Power and communication intertwined
- Must turn radio off to conserve power
 - Reducing transmissions is not enough
- Duty cycling slightly changes things
 - Non-atomic, non-synchronous
 - Broadcast gets expensive
 - But it does not fundamentally change the semantics

Conclusions

- Lightweight, low-power IP
 - Memory
 - Power
- The memory vs performance trade-off
 - API changes
- The power vs communication trade-off
 - Changes to protocols may be needed



Thank you

<http://www.sics.se/contiki/>

The screenshot shows the Contiki website homepage. At the top, the logo "Contiki" is displayed with the tagline "The Operating System for Connecting the Next Billion Devices - the Internet of Things". The left sidebar contains navigation links such as "Home", "About Contiki", "Download", "Instant Contiki", "Install and Compile", "Documentation", "Publications and Talks", "Contiki Projects", "Mailing lists", "Changelog", and "IPv6 FAQ". Below these are "Statistics" (Visitors: 2016696), "Article Categories", "Current Events", "Developers", "Events", "News", "Perspective", "Platforms", "Projects", "Tutorials", and "All". A "User Menu" section includes "Profile" and "Administrative Tasks". The main content area features a featured article titled "IPSN2010 Demo: An IP-based Sensor Network with Augmented Reality" by Adam Dunkels, dated Sunday, 29 August 2010. This article includes a YouTube video player showing a demo of sensor data displayed over a tag. Below the video, there is a paragraph of text and a "Read more..." link. To the right of the video, there are two news snippets: "Now Available from Amazon.com: Interconnecting Smart Objects with IP - The Next Internet" and "Talk on IP-based sensor Networks and the Internet of Things". The right sidebar contains a "Contiki Tweets" section with two tweets, a "Search Contiki Archive" search box, and a "News from the World" section listing various news items.